(Randomized) Localized Model Order Reduction

Kathrin Smetana (University of Twente)

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ICERM Workshop "Algorithms for Dimension and Complexity Reduction"

EL OQO

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Motivation

- Model order reduction ...
 - ... allows to perform computations for many different configurations (parameters, geometry,...) very fast
 - ... without jeopardizing accuracy
- Topic of this talk: Localization and randomization facilitate (nearly) real-time simulations of large-scale problems



Outline

- Projection-based model order reduction in a nutshell
 - Randomized error estimation
- Localized Model Order Reduction
 - Constructing optimal local approximation spaces (in space)
 - Approximating optimal local approximation spaces via random sampling
 - Generating quasi-optimal local approximation spaces in time by random sampling

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Parametrized Partial Differential Equation

- Parameter vector $\mu \in \mathcal{P}$; compact parameter set $\mathcal{P} \subset \mathbb{R}^{P}$
- ▶ Parametrized PDE: Given any $\mu \in \mathcal{P}$, find $u(\mu) \in X$, s.th.

$$A(\mu)u(\mu) = f(\mu)$$
 in X'.

- $\Omega \subset \mathbb{R}^3$: bounded domain with Lipschitz boundary $\partial \Omega$
- $H^1_0(\Omega)^d \subset X \subset H^1(\Omega)^d$ (d = 1, 2, 3); X': dual space
- $A(\mu) : X \rightarrow X'$: inf-sup stable, continuous linear differential operator
- $f(\mu): X \to \mathbb{R}$: continuous linear form

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- High-dimensional discretization:
- Introduce high-dimensional FE space X^N ⊂ X with dim(X^N) = N (assume small discretization error)
- High-dimensional approximation: Given any $\mu \in \mathcal{P}$, find $u^{\mathcal{N}}(\mu) \in X^{\mathcal{N}}$, s.th.

$$A(\mu)u^{\mathcal{N}}(\mu) = f(\mu) \text{ in } X^{\mathcal{N}'}.$$

▶ Issue: Require $u^{\mathcal{N}}(\mu)$ in real time and/or for many $\mu \in \mathcal{P}$.

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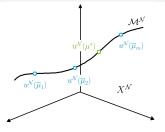
$$\underline{A}(\mu)\underline{\underline{\mu}}^{\mathcal{N}}(\mu) = \underline{f}(\mu) \quad \underline{A}(\mu) \in \mathbb{R}^{\mathcal{N} \times \mathcal{N}}, \underline{f}(\mu) \in \mathbb{R}^{\mathcal{N}}.$$

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Projection-based model order reduction: key concept

- Exploit: $u^{\mathcal{N}}(\mu)$ belongs to "solution manifold" $\mathcal{M}^{\mathcal{N}} = \{u^{\mathcal{N}}(\mu) \mid \mu \in \mathcal{P}\} \subset X^{\mathcal{N}}$ of typically very low dimension
- ▶ Offline: Construct reduced space X^N from solutions u^N(µ
 _i), i = 1,..., N (e.g. by a Greedy algorithm, Proper Orthogonal Decomposition,...)



Online: Galerkin projection on X^N: Given any µ* ∈ P, find u^N(µ*) ∈ X^N, s.th.

$$A(\mu^*)u^N(\mu^*) = f(\mu^*)$$
 in $(X^N)'$.



Construction of reduced basis B via randomization

- First Goal: Given a matrix $S \in \mathbb{R}^{m \times n}$ and an integer k find an orthonormal matrix Q of rank k such that $S \approx QQ^*S$.
- Approach:
- Draw k random vectors $r_j \in \mathbb{R}^n$ (say standard Gaussian)
- Form sample vectors $y_j = Sr_j \in \mathbb{R}^m$ $j = 1, \dots, k$.
- Orthonormalize $y_j \longrightarrow q_j$, j = 1, ..., k and define $Q = [q_1, ..., q_k]$
- ▶ Result: If S has exactly rank k then q_j, j = 1,..., k span the range of S at high probability. But also in the general case q_j, j = 1,..., k often perform nearly as good as the k leading left singular vectors of S
- Compute randomized SVD:
- Form $C = Q^*S$ which yields $S \approx QC$
- Compute SVD of of the small matrix $C = \widetilde{U}\Sigma V^*$ and set $B = Q\widetilde{U}$

For a review see for instance [Halko, Martinsson, Tropp 2011]

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Works also if S is not a data matrix but some linear map which is approximately low rank

References for randomized construction of reduced models

- Hochman et al 2014
- Alla, Kutz 2015
- Zahm, Nouy 2016
- Balabanov, Nouy 2019, 2019
- Cohen, Dahmen, DeVore, Nichols 2020
- Saibaba 2020

A posteriori error estimation

- A posteriori error estimator is important both
 - to construct reduced order models via the greedy algorithm
 - to certify the approximation: how large is the error (in some Qol)?

Proposition (A posteriori error bound)

The error estimator $\widetilde{\Delta}_{N}(\mu) = \beta_{LB}(\mu)^{-1} \|f(\mu) - A(\mu)u^{N}(\mu)\|_{X^{N'}}$ with $\beta_{LB}(\mu) \leq \beta_{N}(\mu)$ satisfies

$$\|u^{\mathcal{N}}(\mu) - u^{\mathcal{N}}(\mu)\|_{X} \leq \widetilde{\Delta}_{\mathcal{N}}(\mu) \leq \frac{\gamma_{\mathcal{N}}(\mu)}{\beta_{LB}(\mu)} \|u^{\mathcal{N}}(\mu) - u^{\mathcal{N}}(\mu)\|_{X},$$

where
$$\beta_{\mathcal{N}}(\mu) := \inf_{v \in X^{\mathcal{N}}} \sup_{w \in X^{\mathcal{N}}} \frac{\langle A(\mu)v, w \rangle}{\|v\|_X \|w\|_X}$$
 and $\gamma_{\mathcal{N}}(\mu) = \sup_{v \in X^{\mathcal{N}}} \sup_{w \in X^{\mathcal{N}}} \frac{\langle A(\mu)v, w \rangle}{\|v\|_X \|w\|_X}.$

 Problem: Good estimate of stability constants often computationally infeasible; using simply the residual may perform very poorly, especially say for Helmholtz-type problems.

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References:

- KS, Zahm, Patera, Randomized residual-based error estimators for parametrized equations. SIAM J. Sci. Comput., 2019.
- KS, Zahm, Randomized residual-based error estimators for the proper generalized decomposition approximation of parametrized problems, Internat. J. Numer. Methods Engrg., to appear, 2020.

References for randomization within error estimation

- Cao, Petzold 2004, Homescu, Petzold, Serban 2005
- Drohmann, Carlberg 2015, Trehan, Carlberg, and Durlofsky 2017
- Manzoni, Pagani, Lassila 2016
- Janon, Nodet, Prieur 2016
- Zahm, Nouy 2016
- Buhr, KS 2018
- Balabanov, Nouy 2019
- Eigel, Schneider, Trunschke, Wolf 2020

Randomized a posteriori error estimation

- Goal: Develop a posteriori error estimator for model order reduction that does not contain constants whose estimation is expensive (avoid estimating inf-sup constant and thus improve effectivity of estimator)
- Setting: We query a finite number of parameters for which we want to estimate the approximation error; allows computing statistics in UQ
- Approach: Exploit concentration inequalities:

Proposition (Concentration inequality, Johnson-Lindenstrauss)

Choose rows of matrix $\Phi \in \mathbb{R}^{K \times N}$ say as K independent copies of standard Gaussian random vectors scaled by $1/\sqrt{K}$ and let $S \subset \mathbb{R}^N$ be a finite set. Moreover, assume $K \ge (C(z)/\varepsilon^2) \log(\#S/\delta)$. Then we have

$$\mathbb{P}\left\{(1-\varepsilon)\|x-y\|_2^2 \leqslant \|\Phi x - \Phi y\|_2^2 \leqslant (1+\varepsilon)\|x-y\|_2^2 \quad \forall x, y \in \mathcal{S}\right\} \ge 1-\delta.$$

see for instance [Boucheron, Lugosi, Massart 2012], [Vershynin 2018]

Assumptions on random vector

• $Z \in \mathbb{R}^{\mathcal{N}}$: random vector such that

$$\|v\|_{\Sigma}^2 = v^T \Sigma v = \mathbb{E}((Z^T v)^2) \quad \forall v \in \mathbb{R}^N,$$

where Σ is matrix e.g. associated with H^1 - or L^2 -inner product or a quantity of interest

 $\implies (Z^T v)^2$ is an unbiased estimator of $||v||_{\Sigma}^2$

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 - For simplicity: Assume $Z \sim \mathcal{N}(0, \Sigma)$ is a Gaussian vector with zero mean and covariance matrix Σ

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- $\implies (Z^T v)^2$ is an unbiased estimator of $\|v\|_{\Sigma}^2$
 - For simplicity: Assume $Z \sim \mathcal{N}(0, \Sigma)$ is a Gaussian vector with zero mean and covariance matrix Σ
 - Z_1, \ldots, Z_K : K independent copies of Z
 - Consider the following (unbiased) Monte-Carlo estimator of $\|v\|_{\Sigma}^2$

$$\frac{1}{K}\sum_{i=1}^{K}(Z_i^T v)^2.$$

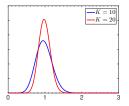
Norm estimate

Proposition (Concentration inequality (KS, Zahm, Patera 2019))

Given a finite set of parameters $S = \{\mu_1, \ldots, \mu_S\} \subset \mathcal{P}$, a failure probability $0 < \delta < 1$, $w \in \mathbb{R}$, $w > \sqrt{e}$, we have for

$$\mathcal{K} \geqslant rac{ \log(\#\mathcal{S}) + \log(\delta^{-1}) }{\log(w/\sqrt{e})}$$
 that

$$\mathbb{P}\left\{\frac{\|\underline{e}(\mu_j)\|_{\Sigma}^2}{w^2} \leqslant \frac{1}{K} \sum_{i=1}^{K} (Z_i^T \underline{e}(\mu_j))^2 \leqslant w^2 \|\underline{e}(\mu_j)\|_{\Sigma}^2, \ \forall \mu_j \in \mathcal{S}\right\} \ge 1 - \delta.$$



- chi-squared distribution
- concentration around 1 (that means error estimator has close to perfect effectivity 1)

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	<i>w</i> = 2	<i>w</i> = 3	<i>w</i> = 4	<i>w</i> = 5	w = 10
#S = 1	24	8	6	5	3
#S = 100	48	16	11	9	6
#S = 1000	60	20	13	11	7
$\#S=10^6$	96	31	21	17	11

Table: Values for K that guarantee (1) for all $\mu_j \in S$ with $\delta = 10^{-2}$.

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Define
$$\Delta(\mu) := \left(\frac{1}{K} \sum_{i=1}^{K} (Z_i^T \underline{e}(\mu))^2 \right)^{1/2}$$

Problem: estimator $\Delta(\mu) = \left(\frac{1}{K}\sum_{i=1}^{K} (Z_i^T(\underline{u}^{\mathcal{N}}(\mu_j) - \underline{u}^{\mathcal{N}}(\mu_j)))^2\right)^{1/2}$ involves high-dimensional finite element solution \implies Computationally infeasible in the online stage

A fast-to-evaluate randomized error estimator

Exploit error residual relationship

$$Z_i^T \underline{e}(\mu) = Z_i^T \underline{A}(\mu)^{-1} \underbrace{(\underline{f}(\mu) - \underline{A}(\mu)\underline{u}^N(\mu)}_{\text{residual } \underline{r}(\mu):=} = \underbrace{(\underline{A}(\mu)^{-T} Z_i)^T \underline{r}(\mu)}_{\text{dual problem}}$$

▶ Define solutions of dual problems with random right-hand sides Z_i:

$$\underline{Y}_i^{\mathcal{N}}(\mu) := \underline{A}(\mu)^{-T} Z_i$$

Approximation of the dual solutions via model order reduction:

$$\underline{y}_i^{\mathcal{N}}(\mu) pprox \underline{y}_i^{\mathcal{N}_{du}}(\mu) \in \widetilde{\mathcal{Y}} \subset X^{\mathcal{N}}; \quad \widetilde{\mathcal{Y}}: \text{ dual reduced space.}$$

Define fast-to-evaluate randomized error estimator

$$\Delta^{N_{du}}(\mu) := \left(\frac{1}{\kappa} \sum_{i=1}^{\kappa} (\underline{y}_{i}^{N_{du}}(\mu)^{T} \underline{r}(\mu))^{2} \right)^{1/2}$$

A fast-to-evaluate randomized error estimator

Proposition

Choose $S \in \mathbb{N}$ in the offline stage. Then, in the online stage for any given $w > \sqrt{e}$ and $\delta > 0$ we have for S different parameters values μ_j , j = 1, ..., S in a finite parameter set $S = \{\mu_1, ..., \mu_S\}$ and

$$K \ge \frac{\log(S) + \log(\delta^{-1})}{\log(w/\sqrt{e})} \qquad that \quad \Delta^{N_{du}}(\mu_j) := \left(\frac{1}{K} \sum_{i=1}^{K} (\underline{y}_i^{N_{du}}(\mu_j)^T \underline{r}(\mu_j))^2 \right)^{1/2}$$

satisfies

$$\mathbb{P}\Big\{(\alpha w)^{-1}\Delta^{N_{du}}(\mu_j) \leqslant \|\underline{e}(\mu_j)\|_{\Sigma} \leqslant (\alpha w)\Delta^{N_{du}}(\mu_j), \quad \mu_j \in \mathcal{S}, \Big\} \ge 1-\delta,$$

where

$$\alpha = \max_{\mu \in \mathcal{P}} \left(\max\left\{ \frac{\Delta(\mu)}{\Delta^{\textit{N}_{\textit{du}}}(\mu)} \,,\, \frac{\Delta^{\textit{N}_{\textit{du}}}(\mu)}{\Delta(\mu)} \right\} \right) \geqslant 1.$$

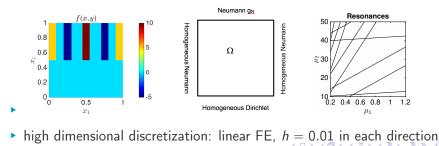
Numerical experiments: acoustics in 2D

• Consider on
$$\Omega = (0,1) \times (0,1)$$

$$\begin{split} -\partial_{x_1x_1} u(x;\mu) - \mu_1 \partial_{x_2x_2} u(x;\mu) - \mu_2 u(x;\mu) &= f(x) & \text{ in } \Omega, \\ u(x;\mu) &= 0 & \text{ on the bottom}, \\ \nabla u(x;\mu) \cdot n &= 0 & \text{ on the sides}, \end{split}$$

$$\kappa(\mu_1) \nabla u(x;\mu) \cdot n = \cos(\pi x)$$
 on the top.

• $m \in \mathcal{P} = [0.2, 1.2] \times [10, 50]$



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Histograms of effectivity $\Delta^{N_{du}}/\|u^{\mathcal{N}}(\mu) - u^{\mathcal{N}}(\mu)\|_{H^1(\Omega)}$

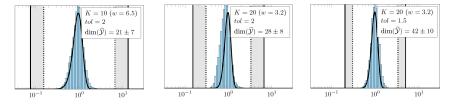


Figure: $\#S = 10^4$, $N_{primal} = 20$, q = 0.99, 100 realizations, vertical dashed lines: 1/w and w, grey area: 1/(tol w) and tol w, where $\alpha \approx tol$, solid lines: chi-squared distribution

3 × 3 = 3 0 0 0

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References:

- Review: Buhr, Iapichino, Ohlberger, Rave, Schindler, and KS. Localized model reduction for parameterized problems. Invited book chapter in Handbook on Model Order Reduction. Walter De Gruyter GmbH, Berlin, 2020; also on arXiv.
- KS, Patera, Optimal local approximation spaces for component-based static condensation procedures, SIAM J. Sci. Comput., 2016.

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Localized model order reduction

Limitations of standard model order reduction approach:

- Curse of parameter dimensionality: many parameters require prohibitively large reduced spaces
- No topological flexibility (although geometric variation is possible)
- Possibly high computational costs in the offline stage



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→ Localized model order reduction

Further advantages:

- Allows to use different (sizes of) reduced spaces in different parts of the domain (similar to hp-methods)
- (Local) changes of the PDE, the geometry in the online stage are possible

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Construction of local reduced spaces, some references

Existing approaches ...

- ... either provided a fast convergence but error analysis seems challenging: [Eftang, Patera 13], [Martini, Rozza, Haasdonk 15], ...
- ... or came with a rigorous error analysis but slow convergence: [Hetmaniuk, Lehoucq 10], [Jakobsson, Bengzon, Larson 11], [Hetmaniuk, Klawonn 14], ...

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- Idea: Use concepts from multiscale methods introduced in [Babuška, Lipton 11], [Malqvist, Peterseim 14] that ...
 - ... rely on the decay behavior of the solution of certain PDEs even for rough coefficients
 - ... and the compactness of certain operators thanks to the Caccioppoli inequality (bounds energy norm of solutions of the PDE by L²-norm on a larger domain)

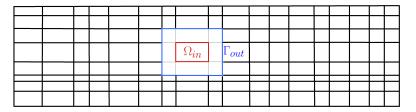
→ Yields superalgebraic convergence and rigorous error analysis

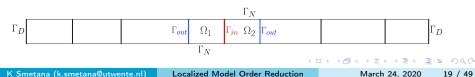
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Localized model order reduction

Challenges:

- We can only exploit that the global solution solves PDE locally
- But: No knowledge of the trace of the global solution on Γ_{out}
- \implies Infinite dimensional parameter space





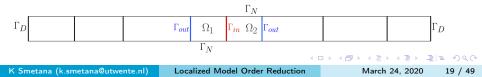
Localized model order reduction

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- → Infinite dimensional parameter space

Idea:

- Restrict to space of functions that solve the PDE locally on Ω for arbitrary boundary conditions on Γ_{out}
- Exploit that for those local solutions we have a very fast decay of higher frequencies from Γ_{out} to Ω_{in}, Γ_{in} (\rightarrow Caccioppoli inequality)
- yields optimal local approximation spaces in the sense of Kolmogorov



Optimal local approximation spaces

Definition (Kolmogorov n-width, optimal subspaces (Kolmogoroff 1936))

S, R Hilbert spaces, R^n : subspace of R, dim $R^n = n$, $T : S \rightarrow R$ linear, continuous operator. The Kolmogorov *n*-width is defined as

$$d_n(T(S); R) := \inf_{\dim R^n = n} \sup_{\eta \in S} \inf_{\zeta \in R^n} \frac{\|T(\eta) - \zeta\|_R}{\|\eta\|_S}$$

A subspace R^n with dim $R^n \leq n$, that satisfies

$$d_n(T(S); R) = \sup_{\eta \in S} \inf_{\zeta \in R^n} \frac{\|T(\eta) - \zeta\|_R}{\|\eta\|_S}$$

is called an optimal subspace.

Motivation: separation of variables

• Consider
$$\Omega = (-5,5) \times (0,1)$$

$$-\Delta u = 0, \quad \text{in } \Omega,$$

$$\frac{du}{dy}(x,1) = \frac{du}{dy}(x,0) = 0.$$

plus: arbitrary Dirichlet boundary conditions on Γ_{out}.



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Motivation: separation of variables

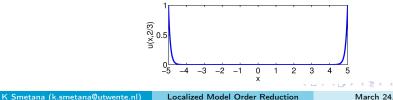
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, in Ω , $\frac{du}{dy}(x, 1) = \frac{du}{dy}(x, 0) = 0$.

- plus: arbitrary Dirichlet boundary conditions on Γ_{out} .
- separation of variables: all harmonic functions on Ω have the form

$$u(x, y) = a_0 + b_0 x + \sum_{n=1}^{\infty} \cos(n\pi y) [a_n \cosh(n\pi x) + b_n \sinh(n\pi x)]$$

• Example: Prescribe $cos(3\pi y)$ on Γ_{out} and thus n = 3:



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- \implies Extremely rapid and exponential decay of the cos-functions in the interior of Ω for higher *n*.
- ⇒ Most harmonic extensions of the basis functions $cos(n\pi y)$, $n = 0, ..., \infty$ are practically zero on Γ_{in} .
- \implies A reduced space of very low dimension on Γ_{in} will already yield a very good approximation!

Motivation: separation of variables

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, in Ω , $\frac{du}{dy}(x, 1) = \frac{du}{dy}(x, 0) = 0$.

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Question: How can we generalize this idea?

The space of all local solutions of the PDE on $\boldsymbol{\Omega}$

 \blacktriangleright Consider the space of all local solutions of the PDE1 on Ω

$$\mathcal{H} := \{ w \in H^1(\Omega) : \text{with } Aw = 0 \in X' \}.$$

- global solution of the PDE restricted to Ω lies in \mathcal{H} !
- We are interested in $u|_{\Gamma_{in}}$ or $u|_{\Omega_{in}}$ and thus introduce

$$R := \{ w |_{\Gamma_{in}}, w \in \mathcal{H} \} \text{ or } R := \{ w |_{\Omega_{in}}, w \in \mathcal{H} \},$$

and $S := \{ w |_{\Gamma_{out}}, w \in \mathcal{H} \}.$

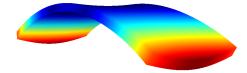
¹For theoretical purposes one needs to consider the quotient space $\tilde{\mathcal{H}} := \mathcal{H}/\ker(A)$ at certain instances.

We introduce a transfer operator

 $T: S \to R$

For $w \in \mathcal{H}$ and thus $w|_{\Gamma_{out}} \in S$ we define

$$T(w|_{\Gamma_{out}}) := w|_{\Gamma_{in}}$$
 or $T(w|_{\Gamma_{out}}) := w|_{\Omega_{in}}$.



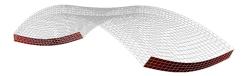
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- We introduce a transfer operator $T: S \rightarrow R$
- For $w|_{\Gamma_{out}} \in S$ we define $T(w|_{\Gamma_{out}}) := w|_{\Gamma_{in}}$ or $T(w|_{\Gamma_{out}}) := w|_{\Omega_{in}}$.
- T is compact thanks to the Caccioppoli inequality:

Lemma (Caccioppoli inequality for heat conduction)

Let $\kappa \in L^{\infty}(\Omega)$ fulfill $0 < \kappa_0 \le \kappa \le \kappa_1$ with constants κ_0, κ_1 , define $X^0 = \{v \in H^1(\Omega), v |_{\Gamma_{out}} = 0\}$, let $u \in X := \{v \in H^1(\Omega), v |_{\Gamma_{out}} = g\}$ satisfy

$$\int_{\Omega} \kappa \nabla u \cdot \nabla v = 0 \quad \forall v \in X^{0}.$$

Then on $\Omega^* \subsetneq \Omega^{**} \subset \Omega$ with $dist(\partial \Omega^* \setminus \partial \Omega, \partial \Omega^{**} \setminus \partial \Omega) > \varrho > 0$ there holds

$$\int_{\Omega^*} \kappa |\nabla u|^2 \, dx \leq \frac{c}{\varrho^2} \|u\|_{L^2(\Omega^{**} \setminus \Omega^*)}^2.$$

- We introduce a transfer operator $T : S \rightarrow R$
- For $w|_{\Gamma_{out}} \in S$ we define $T(w|_{\Gamma_{out}}) := w|_{\Gamma_{in}}$ or $T(w|_{\Gamma_{out}}) := w|_{\Omega_{in}}$.
- T is compact thanks to the Caccioppoli inequality.
- Introduce adjoint operator T^* and consider the eigenvalue problem

 $T^*Tw|_{out} = \lambda w|_{out}$ for $w \in \mathcal{H}$.

• Equivalent formulation: Find $(\varphi_j, \lambda_j) \in (\mathcal{H}, \mathbb{R}^+)$ such that

 $(\varphi_j|_{D_{in}}, w|_{D_{in}})_R = \lambda_j (\varphi_j|_{\Gamma_{out}}, w|_{\Gamma_{out}})_S \forall w \in \mathcal{H}, D_{in} = \Gamma_{in}, \Omega_{in}$

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Transfer eigenvalue problem

Proposition (Transfer eigenvalue problem)

• φ_j and λ_j : eigenfunctions and eigenvalues of the transfer eigenvalue problem: Find $(\varphi_j, \lambda_j) \in (\mathcal{H}, \mathbb{R}^+)$ such that

 $(\varphi_j|_{D_{in}}, w|_{D_{in}})_R = \lambda_j (\varphi_j|_{\Gamma_{out}}, w|_{\Gamma_{out}})_S \forall w \in \mathcal{H}, D_{in} = \Gamma_{in}, \Omega_{in}$

- List λ_j such that $\lambda_1 \ge \lambda_2 \ge ...$, and $\lambda_j \to 0$ as $j \to \infty$.
- The optimal space on Γ_{in} or Ω_{in} is given by

$$R^n := \operatorname{span}\{\phi_1^{sp}, ..., \phi_n^{sp}\}, \ \phi_j^{sp} = T\varphi_j|_{\Gamma_{out}}, \quad j = 1, ..., n.$$

$$d_n(T(S); R) = \sup_{\xi \in S} \inf_{\zeta \in R^n} \frac{\|T\xi - \zeta\|_R}{\|\xi\|_S} = \sqrt{\lambda_{n+1}}$$

A priori error bound

Proposition (A priori error bound (KS, Patera 2016))

u: (exact) solution,

 u^n : continuous port reduced static condensation solution employing the optimal port space \mathbb{R}^n .

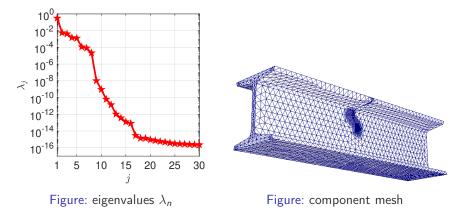
We have:

$$\frac{\||\boldsymbol{u}-\boldsymbol{u}^n\||}{\||\boldsymbol{u}\||} \leqslant C_1(\Omega)\sqrt{\lambda_{n+1}},$$

where $C_1(\Omega)$ does neither depend on u nor on u^n .

Numerical experiments for isotropic linear elasticity

cracked I-Beam, uniform Young's modulus $E_i = 1$ in both components

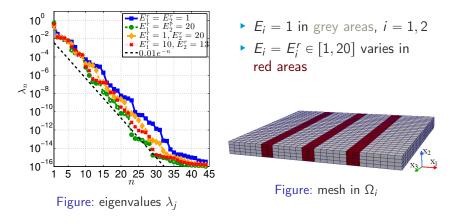


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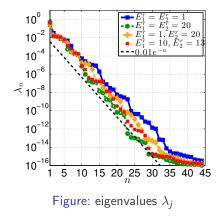
Numerical experiments for isotropic linear elasticity

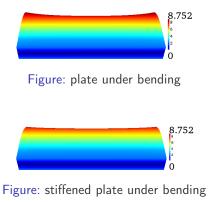
Stiffened plate — simplified model for ship stiffener



Numerical experiments for isotropic linear elasticity

Stiffened plate — simplified model for ship stiffener





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Comparison with other reduced interface spaces

Solid beam, $E_i = E_i^r = 1^2$, $g|_{\Gamma_1} = (0, 0, 0)^T$, $g|_{\Gamma_2} = (1, 1, 1)^T$

- Legendre polynomials: components of the displacement are solutions of scalar singular
 Sturm-Liouville problems
- Empirical port modes constructed by a pairwise training algorithm [Eftang, Patera 2013]
- spectral modes constructed by the spectral greedy

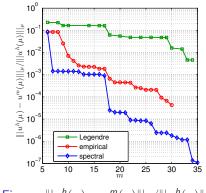


Figure: $|||u^{h}(\mu) - u^{m}(\mu)|||_{\mu}/|||u^{h}(\mu)|||_{\mu}$

 ${}^{2}\mathcal{P}_{i} = [1, 10] \times [1, 1] \text{ for } \mu_{i} = (E_{i}, E_{i}^{r})$

K Smetana (k.smetana@utwente.nl)

Localized Model Order Reduction

March 24, 2020

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Numerical experiments: shiploader³



³Results by company Akselos S.A.; KS has no financial interest in Akselos S.A. - o.c.

Numerical experiments: shiploader³



Figure: shiploader

- discretization with FEM:
 >20 millions of DOFs
- size of Schur complement system: ≈349 000



shiploader with defect

- size of reduced Schur complement system: ≈12 000
- Simulation time with reduced port spaces: ≈ 2 sec

³Results by company Akselos S.A.; KS has no financial interest in Akselos S.A. - 999

Computing an approximation of the transfer eigenvalue problem

Transfer eigenvalue problem: Find $(\varphi_j, \lambda_j) \in (\mathcal{H}, \mathbb{R}^+)$ such that

 $(T^{h}(\varphi_{j}|_{\Gamma_{out}}), T^{h}(w|_{\Gamma_{out}}))_{R} = \lambda_{j} (\varphi_{j}|_{\Gamma_{out}}, w|_{\Gamma_{out}})_{S} \forall w \in \mathcal{H}$

 $\mathcal{H}=\{ \text{ set of all local solutions of the PDE with arbitrary Dirichlet b. c. } \}$

- Introduce a FE discretization with N_{out} degrees of freedom (DOFs) on Γ_{out} and N_{in} DOFs on Γ_{in} or Ω_{in}
- Solve for each basis function on Γ_{out} the PDE locally
 mumber of required local solutions of the PDE scales with the number of DOFs on Γ_{out} and thus depends on the discretization
- Sample and solve generalized eigenvalue problem

$$\Gamma_{out} \qquad \qquad \Gamma_{in} \qquad \qquad \Gamma_{out} \qquad \qquad \qquad \Gamma_{out}$$

Computing an approximation of the transfer eigenvalue problem

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- Semble and solve generalized eigenvalue problem

Problem: For large number of DOFs on Γ_{out} the approximation of the transfer eigenvalue problem can be very/prohibitively expensive especially in 3D

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Outline

- Projection-based model order reduction in a nutshell
 - Randomized error estimation
- Localized Model Order Reduction
 - Constructing optimal local approximation spaces (in space)
 - Approximating optimal local approximation spaces via random sampling
 - Generating quasi-optimal local approximation spaces in time by random sampling

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Reference: Buhr, KS, Randomized Local Model Order Reduction, SIAM J. Sci. Comput., 2018.

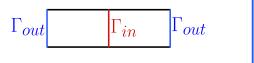
References on randomization in multiscale, domain decomposition methods

- Wang, Vouvakis 2015
- Calo, Efendiev, Galvis, Li 2016
- Owhadi 2015, 2017
- Chen, Li, Lu, and Wright, arXiv:1801.06938; arXiv:1807.08848

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Approximating optimal local spaces with Randomized Linear Algebra⁴

- Prescribe random boundary conditions; in detail choose every coeffcient of a FEM basis function on Γ_{out} as a (mutually independent) Gaussion random variable with zero mean and variance one
- Solve PDE for random boundary conditions numerically and store evaluation of local solution of PDE u^h|_{Γin} or u^h|_{Ωin}.
- Define reduced space R^n_{rand} as the span of n such evaluations $u^h|_{\Gamma_{in}}$ or $u^h|_{\Omega_{in}}$





 ⁴ for a review see [Halko, Martinsson, Tropp 11]
 Image: A transform of the second seco

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- \blacktriangleright Define reduced space R^n_{rand} as the span of n such evaluations $u^h|_{\Gamma_{in}}$ or $u^h|_{\Omega_{in}}$

Questions: What is the quality of such an approximation? (How) can we determine the dimension of the reduced space for a given tolerance?

Probalistic a priori error bound⁵

Proposition (A priori error bound (Buhr, KS 2018))

Under the above assumptions there holds for $n, p \ge 2$

$$\mathbb{E}\left[\sup_{\xi\in S^{h}}\inf_{\zeta\in R_{rand}^{n+p}}\frac{\|T^{h}\xi-\zeta\|_{R}}{\|\xi\|_{S}}\right] \leq \underbrace{C_{h}\left\{\left(1+\frac{\sqrt{n}}{\sqrt{p-1}}\right)\sqrt{\lambda_{n+1}^{h}}+\frac{e\sqrt{n+p}}{p}\left(\sum_{j>n}\lambda_{j}^{h}\right)^{1/2}\right\}}_{\sim c\sqrt{n}\sqrt{\lambda_{n+1}^{h}}}$$

Optimal convergence rate achieved with transfer eigenvalue problem:

$$d_n(T(S); R) = \sup_{\xi \in S} \inf_{\zeta \in R^n} \frac{\|T\xi - \zeta\|_R}{\|\xi\|_S} = \sqrt{\lambda_{n+1}}$$

 ⁵based on results in [Halko, Martinsson, Tropp 11]
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where

$$C_{h} = \sqrt{\frac{\lambda_{max}(\underline{M}_{R})}{\lambda_{min}(\underline{M}_{R})}} \sqrt{\frac{\lambda_{max}(\underline{M}_{S})}{\lambda_{min}(\underline{M}_{S})}}$$

- $(\underline{M}_R)_{i,j} = (\psi_j, \psi_i)_R$, ψ_i : FE basis functions
- $(\underline{M}_{S})_{i,j} = (\psi_j, \psi_i)_{S}$, ψ_i : FE basis functions
- p: oversampling parameter

Probablistic a posteriori error bound⁶

Proposition (Probablistic a posteriori error bound (Buhr, KS 2018))

- $\{\underline{\omega}^{(i)} : i = 1, 2, ..., n_t\}$: standard Gaussian vectors
- $D_{S} : \mathbb{R}^{N_{out}} \to S^{h}$; $(c_{1}, ..., c_{N_{out}}) \mapsto \chi$, $\chi = \sum_{i=1}^{N_{out}} c_{i}\psi_{i}$, $\psi_{i} : FE$ basis functions

Define

$$\Delta(n_t, \delta_{\mathrm{tf}}) := \frac{c_{\mathrm{est}}(n_t, \delta_{\mathrm{tf}})}{\sqrt{\lambda_{\min}^{\underline{M}_S}}} \max_{i \in 1, \dots, n_t} \left(\inf_{\zeta \in R_{rand}^n} \| T^h D_S \underline{\omega}^{(i)} - \zeta \|_R \right)$$

Then there holds

$$\sup_{\xi \in S^h} \inf_{\zeta \in R_{rand}^n} \frac{\|T^h \xi - \zeta\|_R}{\|\xi\|_S} \leq \Delta(n_t, \delta_{\mathrm{tf}}) \leq \left(\frac{\lambda_{max}^M}{\lambda_{max}^M}\right)^{1/2} c_{\mathrm{eff}}(n_t, \delta_{\mathrm{tf}}) \sup_{\xi \in S^h} \inf_{\zeta \in R_{rand}^n} \frac{\|T^h \xi - \zeta\|_R}{\|\xi\|_S}$$
with a probability of at least $1 = \delta_{\mathrm{tf}}$

⁶Estimator extends results in [Halko, Martinsson, Tropp 11]; effectivity bound_new a constraint K Smetana@utwente.nl) Localized Model Order Reduction March 24, 2020 33 / 49

Adaptive randomized range finder⁷

- Input: Select tolerance tol, failure probability $\delta_{algofail}$
- While $\Delta(n_t, \delta_{tf}) > tol$
 - Generate random boundary values on Γ_{out}
 - Apply transfer operator T^h to random boundary conditions
 - Add new solution to R_{rand}^n
 - Orthonormalize solutions
 - Update a posteriori error estimator
- ► Output: R_{rand}^n such that $\sup_{\xi \in S^h} \inf_{\zeta \in R_{rand}^n} \frac{\|T^h \xi \zeta\|_R}{\|\xi\|_S} \leq tol$ with probability at least $1 \delta_{algofail}$

⁷adapted from [Halko, Martinsson, Tropp 11]

Numerical Experiments for analytic test problem

Numerical Experiments: interfaces

- local (oversampling) domain $\Omega := (-1, 1) \times (0, 1)$
- Consider PDE: $-\Delta u = 0$ in Ω
- Goal: Construct reduced space on Γ_{in}

$$\Gamma_{out}$$
 Γ_{in} Γ_{out}
Figure: Ω

Heat conduction: $-\Delta u = 0$ on $\Omega = (-1, 1) \times (0, 1)$

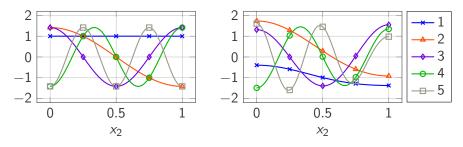


Figure:

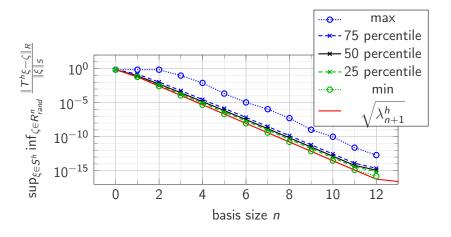
optimal basis

basis generated by randomized range finder algorithm

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Heat conduction: $-\Delta u = 0$ on $\Omega = (-1, 1) \times (0, 1)$



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Heat conduction: $-\Delta u = 0$ on $\Omega = (-1, 1) \times (0, 8)$

CPU times

Properties of basis generation

	Algorithm 2	Scipy/ARPACK
(resulting) basis size <i>n</i>	39	39
operator evaluations	59	79
adjoint operator evaluations	0	79
execution time in s (without factorization)	20.4 s	47.9 s

Table: CPU times; Target accuracy tol= 10^{-4} , number of testvectors $n_t = 20$, failure probability $\delta_{\text{algofail}} = 10^{-15}$; unknowns of corresponding problem 638,799

Numerical Experiments for a transfer operator with slowly decaying singular values

Numerical Experiments: subdomains

- ▶ local (oversampling) domain $\Omega := (-2, 2) \times (-0.25, 0.25) \times (-2, 2)$
- Consider PDE: linear elasticity in Ω (isotropic, homogeneous)
- Goal: Construct reduced space on $\Omega_{in} = (-0.5, 0.5) \times (-0.25, 0.25) \times (-0.5, 0.5)$

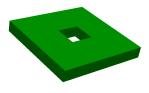


Figure: $\Omega \setminus \Omega_{in}$

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Linear elasticity on $\Omega := (-2, 2) \times (-0.5, 0.5) \times (-2, 2)$

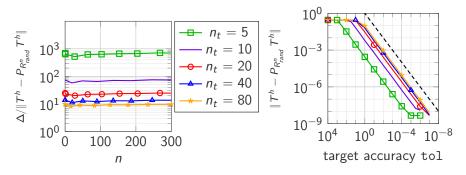
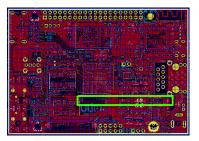


Figure: Convergence behavior of adaptive algorithm (left) and effectivity of a posteriori error estimator $\Delta/||T^h - P_{R_{rand}^n}T^h||$ (right) for increasing number of test vectors n_t .

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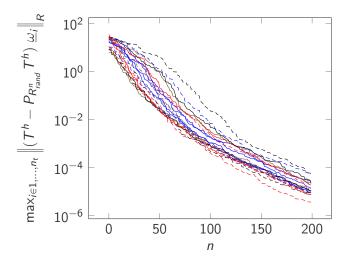
Olimex A64: Maxwell's equation (results by Andreas Buhr)





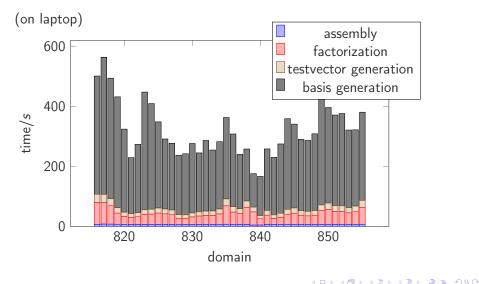
- global discretization: about 65 million degrees of freedom
- 1120 subdomains

Error Estimator Decay



= 200

CPU timings



Outline

- Projection-based model order reduction in a nutshell
 - Randomized error estimation
- Localized Model Order Reduction
 - Constructing optimal local approximation spaces (in space)
 - Approximating optimal local approximation spaces via random sampling
 - Generating quasi-optimal local approximation spaces in time by random sampling

References:

- KS, Schleuß, Optimal local approximation spaces for parabolic problems, in preparation.
- KS, ter Maat, Generating quasi-optimal local approximation spaces in time by random sampling, in preparation.

Decay behavior of solutions of certain PDEs in time

The solution space of certain system of ordinary/partial differential equations in time is locally low-rank

• Consider

$$\begin{aligned} \partial_t u - \operatorname{div}(\kappa(x,t)\nabla u) &= 0, \quad \text{in } D\times(0,T), \\ u(x,t) &= 0 \text{ on } \partial D, \quad u(x,0) = u_0(x). \end{aligned}$$

- There holds: $\|u(\cdot,t)\|_{L^2(D)} \leq e^{-C(\kappa)t} \|u_0\|_{L^2(D)}$.
- Idea: Exploit decay behavior to efficiently construct local reduced or multiscale spaces in time.

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A compact transfer operator for time-dependent problems

• Define transfer operator $T_{0 \to t^*} : L^2(D) \to \mathcal{H}_{t^*}$ that solves PDE for arbitrary initial conditions and evaluates corresponding solution in t^* , where

$$\mathcal{H}_{t^*} := \left\{ w(\cdot, t^*) \in L^2(D) \ : \ w \text{ solves PDE with } w(\cdot, 0) \in L^2(D), f \equiv 0 \right\}.$$



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► Heat equation with rough coefficients: T_{0→t*} is compact thanks to the Caccioppoli inequality:

Proposition (Caccioppoli inequality in time (KS, terMaat 2020))

Let w satisfy the weak form of the heat equation with right-hand side $f \equiv 0$ and arbitrary initial conditions w(x, 0) and let $\varrho \in \mathbb{R}$ with $\varrho > 0$. Then, we have

$$\|w(\cdot,t^*)\|_{L^2(D)}^2 + \|\kappa^{1/2}\nabla w\|_{L^2((\varrho,T-\varrho),L^2(D))} \leq \frac{1}{\varrho} \|w\|_{L^2(I,L^2(D))}^2.$$

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► Heat equation with rough coefficients: T_{0→t*} is compact thanks to the Caccioppoli inequality.

Proposition (Optimal approximation spaces (KS, terMaat 2020))

The optimal approximation space in \mathcal{H}_t is given by

$$\mathcal{H}^n_{t*} := \operatorname{span}\{\phi_1^{t^*}, ..., \phi_n^{t^*}\}, \qquad \textit{where } \phi_j^{t^*} = \mathcal{T}_{0 \to t^*}\varphi_j^{t^*}, \quad j = 1, ..., n,$$

and $\varphi_j^{t^*}$ eigenfunctions of the transfer eigenvalue problem: Find $(\varphi_j^{t^*}, \lambda_j^{t^*}) \in (\mathcal{H}_0, \mathbb{R}^+)$ such that

$$(\mathcal{T}_{0\to t^*}\varphi_j^{t^*}, \mathcal{T}_{0\to t^*}w)_{L^2(D)} = \lambda_j^{t^*}(\varphi_j^{t^*}, w)_{L^2(D)} \quad \forall w \in \mathcal{H}_0.$$

K Smetana (k.smetana@utwente.nl)

Localized Model Order Reduction

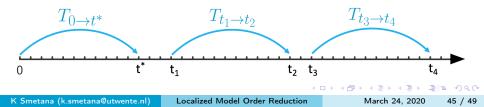
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Approximation of optimal spaces by random sampling

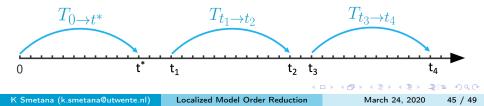
- Apply $T_{0 \rightarrow t^*}$ to *n* mutually independent random initial conditions.
- Start collecting snapshots after a certain amount of time steps to let higher frequencies decay.
- Add snapshots of simulation with prescribed initial condition u₀ for few time steps to snapshot set.
- Apply SVD to collection of all snapshots to construct reduced space.



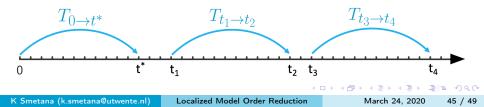
- ▶ To capture time-dependent data start at different points in time
- Define transfer operator T_{ti→tj} that solves PDE for arbitrary initial conditions, arbitrary starting time t_i and evaluates corresponding solution in t_j



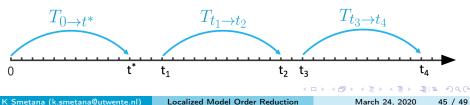
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- Theory for $T_{0 \rightarrow t^*}$ can directly be extended to $T_{t_i \rightarrow t_j}$
- Choose *n* random points of time t_i , i = 1, ..., n and apply $T_{t_i \rightarrow t_j}$ to a random initial condition (mutually independent).
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- Advantage: reduced models can be constructed in parallel

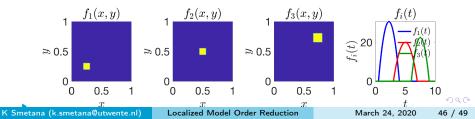


Numerical experiments: Stove problem

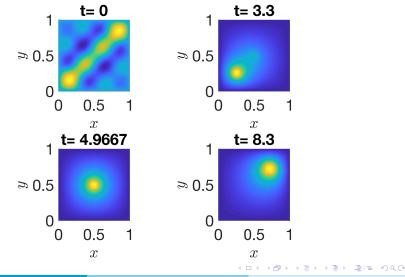
- $\Omega = (0,1) \times (0,1)$, final time T = 10
- Consider:

$$\partial_t u(x, y, t) - \Delta u(x, y, t) = f(x, y, t) \quad \text{in } \Omega \times (0, T),$$
$$u = 0 \quad \text{on } \partial\Omega \times (0, T),$$
$$u(x, y, 0) = \sum_{k=2}^4 \sin(k\pi x) \sin(k\pi y).$$

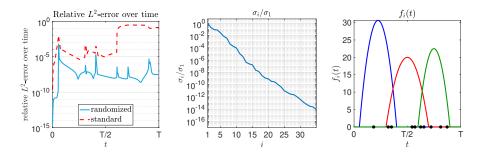
Use FEM with h = 0.01 in x- and y-direction, implicit Euler with 300 time steps



Numerical experiments: solution at different points of time



Numerical experiments: error, singular values, random starting points in time t_i



- Consider 10 different random starting points
- Collecting snapshots between the 12th and 15th time step after t_i
- \Rightarrow Dimension of reduced space is 17

Summary

- Randomized error estimators build on concentration inequalities for Gaussian maps can provide
 - ... a very accurate estimate of the error at high probability
 - ... at low cost.
- Localized model order reduction: Exploit decay behavior of solutions of certain PDEs to construct optimal local approximation spaces
- Randomized methods are well suited to approximate the range of maps that are low-rank; Examples: local solution spaces in space or time
 - Probabilistic a priori error bound/Numerical experiments for local solution in space: convergence rate is only slightly worse compared to the optimal rate (factor \sqrt{n})
 - required number of local solutions of PDE scale (roughly) with size of the reduced space; Numerical experiments: faster than Lanczos

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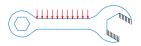
Thank you very much for your attention!

Comparison with Krylov subspace methods

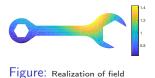
	randomized methods	Krylov subspace methods
computational	stage A: $T_{mult}(k + n_t) + O(k^2m)$	
costs	stage B: $T_{mult}(k) + \mathcal{O}(k^2(m+n))$	ideally $T_{mult}(k) + \mathcal{O}(k^2(m+n))$
stability	inherently stable	inherently unstable
parallelizable	yes	no

Numerical experiments: Linear elasticity with $dim(\mathcal{P}) = 20$

- Consider $-\operatorname{div}(E(m)C : \varepsilon(u(m))) = f$ in Ω with
 - C stiffness and ε strain tensor
 - vertical unitary linear forcing *f* (red arrows)
 - $\bullet\,$ zero Dirichlet boundary conditions at ||||
- E(m): log-normally distributed random field on Ω, use truncated Karhunen-Loève decomposition with 20 terms
- We use a tensor-based model reduction method (PGD) and estimate the relative root mean square error



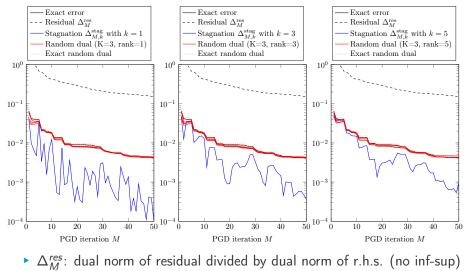




 $\log(E(m))$



Steering the (primal) model reduction approximation



• $\Delta_{M,k}^{stag}$: relative hierarchical error estimator using k increments